
ICMAM 2017 submission 9

1 message

ICMAM 2017 <icmam2017@easychair.org>
To: Hendriko Hendriko <hendriko@pcr.ac.id>

Wed, Jun 21, 2017 at 8:03 AM

Dear authors,

We received your paper:

Authors : Hendriko Hendriko
Title : Analytical Based Inverse Kinematics Method for 5-axis Delta Robot
Number : 9

The paper was submitted by Hendriko Hendriko <h3ndriko@gmail.com>.

Thank you for submitting to ICMAM 2017.

Best regards,
EasyChair for ICMAM 2017.

ICMAM 2017 Acceptance Notification-AM0009

3 messages

icmam <icmam@iacsitp.com>
To: hendriko@pcr.ac.id

Thu, Aug 3, 2017 at 10:31 AM

Full Paper Acceptance Notification

**2017 4th International Conference on Mechatronics, Automation and Manufacturing
(ICMAM 2017)**

Phuket, Thailand, October 13-15, 2017

<http://www.icmam.org/>

Paper ID : AM0009

Paper Title : Analytical Based Inverse Kinematics Method for 5-axis Delta Robot

Dear Hendriko Hendriko, Nurkhamdi, Jajang Jaenudin, Imam M Muthahar,

We're pleased to inform you that your full paper above has passed the review of the conference technical committees and has been accepted for both publication and oral presentation at the conference 2017 4th International Conference on Mechatronics, Automation and Manufacturing (ICMAM 2017), Phuket, Thailand, October 13-15, 2017.

Your paper will be published in International Journal of Materials, Mechanics and Manufacturing (IJMMM), which will be indexed by EI (INSPEC, IET), Chemical Abstracts Services (CAS), Engineering & Technology Digital Library, ProQuest, Crossref, Ulrich's Periodicals Directory, etc.

Registration Instructions

Please follow the six steps below to guarantee your registration be completed on time.

1. Revise your paper according to the review comments in the attachment carefully.

2. Prepare your final revised paper by following the template.

http://www.ijmmm.org/IJMMM_template.doc

3. Complete and Sign the Copyright Form.

<http://www.ijmmm.org/IJMMM.Copyright.doc>

4. Download and complete the Registration Form.

http://www.icmam.org/Regform_Author.doc

5. Finish the payment of Registration fee (The information can be found in the Registration form)

6. Send your Final Revised Paper, Signed Copyright Form, Filled Registration Form (Both .doc and .pdf format), Scanned Payment Proof to us at icmam@iacsitp.com by Registration Deadline (Before September 10, 2017)

Note:

• If you pay by on-line Credit Card Payment, please fill your confirmation number in the registration form after paying.

• If you pay by bank transfer, please scan the payment slip as the payment proof for checking.

If you have any problem, please feel free to contact us via icmam@iacsitp.com. For the most updated information on the conference, please check the conference website at <http://www.icmam.org/>.

As for the accommodation during the conference, we suggest you make early reservation with the conference venue or choose other hotels nearby.

Again, congratulations. We look forward to seeing you in Phuket, Thailand.

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Warm Regards,

Ms. Cherry Chan

ICMAM 2017 Conference Secretary

Email: icmam@iacsitp.com | **Tel.:** +65-31563599 (Singapore); +86-28-86512185 (China)

IJMMM Website: <http://www.ijmmm.org/>; ICMAM Website: <http://www.icmam.org/>

2 attachments

ICMAM 2017 Acceptance Notification-AM0009.pdf
319K



ICMAM 2017 Review Form-AM0009.pdf
137K

Hendriko <hendriko@pcr.ac.id>

Thu, Aug 3, 2017 at 10:41 AM

To: Nur Khamdi <khamdi@pcr.ac.id>, Jajang Jaenudin <jajang@pcr.ac.id>

Satu paper diterima dan siap masuk Jurnal Internasional meski tidak terindeks SCOPUS.
Menunggu satu paper lagi yang sedang di review untuk ICOME di ITS.
Mudah2an yang di ICOME diterima karena publikasinya di jurnal SCOPUS.

Dr. HENDRIKO, M.Eng.

Politeknik Caltex Riau

Jln. Umban Sari No. 1, Rumbai, Pekanbaru - Riau, Indonesia

T : 0761 53939 | F : 0761 554224 | www.pcr.ac.id

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2 attachments

ICMAM 2017 Acceptance Notification-AM0009.pdf
319K



ICMAM 2017 Review Form-AM0009.pdf
137K

Jajang Jaenudin <jajang@pcr.ac.id>

Thu, Aug 3, 2017 at 10:48 AM

To: Hendriko <hendriko@pcr.ac.id>

Cc: Nur Khamdi <khamdi@pcr.ac.id>

Alhamdulillah...

Muantep tenan Pak Ketua.

[Quoted text hidden]

ICMAM 2017 Review Form

Paper ID: AM0009

Paper Title: Analytical Based Inverse Kinematics Method for 5-axis Delta Robot

The above manuscript which was submitted to **2017 4th International Conference on Mechatronics, Automation and Manufacturing (ICMAM 2017)**, the *annual conference of IJMMM Editorial Board* has been reviewed. The author should revise your manuscript according the reviewer's comments as follows, and submit the revised manuscript as your final paper to us by stipulated date.

Recommendation to Editors with <input checked="" type="checkbox"/>					
	Strongly Reject	Reject	Marginally Accept	Accept with revisions	Strong Accept
Recommendation				X	
<p>Expertise: The paper matches to the topic quite well, it could be told the author have done plenty background research for the paper, the method and results are convincingly explanatory, while, some of the references are old given leading edge work, more current references should be added.</p>					
<p>Comments:</p>					