
FAIM 2019: New Submission Received. Contribution ID: 427

1 message

FAIM 2019 Organizers <faim2019@conftool.pro>

Fri, Feb 1, 2019 at 10:43 AM

Reply-To: info@faimconference.com

To: hendriko@pcr.ac.id

Cc: h3ndriko@gmail.com

Dear Dr. Hendriko Hendriko,

We have received your submission. Thank you.

Contribution Details

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Contribution ID : 427

Type : FULL PAPER

Title : Development of invers kinematic method for 6-dof parallel robot using analytical approach

Author(s) : Hendriko, Hendriko

Uploaded Files

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1st file : Contribution_427.docx

Last Upload: 1st Feb 2019, 03:43:43am GMT

With best regards,
Your FAIM 2019 organizers.

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FAIM 2019 - 29th International Conference on Flexible Automation and Intelligent Manufacturing

<https://www.conftool.pro/faim2019/><https://faimconference.com/>

FAIM 2019 Update

1 message

FAIM 2019 Organizers <faim2019@conftool.pro>

Tue, Apr 16, 2019 at 10:46 PM

Reply-To: faimconference2019@gmail.com

To: hendriko@pcr.ac.id

Cc: h3ndriko@gmail.com

Dear Hendriko Hendriko,

Thank you for your patience while the review process have been completed. It has taken a little longer than expected and we understand that people need feedback to organise travel etc.

However all reviews have now been returned and authors will be issued with their feedback this afternoon.

Authors will need to resubmit their papers by April 30th, the organising committee will extend the early bird registration to this date also. Camera ready papers will be submitted using the conftool system as per previous versions, pdf and word copies will be required as will a document illustrating your response to reviewer comments.

A link to FAIM2019 registration page will be provided with your review results. Here you can also book accommodation if desired, although can opt not to.

For those who opted for fast track journal publication, top papers are undergoing a final review, those authors will receive notice before the end of the week.

In the meantime all authors should act on the instructions received from the reviewers in preparing their paper for FAIM2019.

Best regards

FAIM2019 Organising Committee

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FAIM 2019 Review Results

1 message

FAIM 2019 Organizers <faim2019@conftool.pro>

Tue, Apr 16, 2019 at 10:56 PM

Reply-To: faimconference2019@gmail.com

To: hendriko@pcr.ac.id

Cc: h3ndriko@gmail.com

Dear Hendriko Hendriko,

Thank you for your submission to the FAIM2019 conference.

Please see below reviewer comments.

Please comply with these comments and, if invited, resubmit your paper in the agreed format.

Finalised template for FAIM2019 paper submission will be circulated in the next days but we hope that confirmation of your paper status will facilitate travel arrangements.

The review process was considerable and we wish to thank our international panel of reviewers for their contribution.

To register for the conference the link is now available:

<https://campuslifeweb.ul.ie/KxRegistration/FAIM2019>

As previously noted a maximum of two papers may be presented per delegate.

CONTRIBUTION DETAILS

ID: 427

Title: Development of invers kinematic method for 6-dof parallel robot using analytical approach

REVIEW RESULT OF THE PROGRAM COMMITTEE:

This contribution has been accepted as oral presentation. Paper to be included in conference proceedings

Please upload camera ready version in required formats and response to reviewer comments by required deadline.

OVERVIEW OF REVIEWS**Review 1****Contribution of the Submission**

An analytical based approach to calculate the kinematics of 6 DOF delta robot was proposed. The robot consists of six arms connected to moveable platform. Each arm can move independently. A simulation program based on the proposed algorithm was developed using Matlab

Evaluation of the Contribution

Quality of Content (15%): 4
Significance (15%): 6
Originality (15%): 6
Thematic Relevance (15%): 6
Presentation (15%): 6
Overall Recommendation (25%): 6
Total points (out of 100) : 57

Comments for the Authors

- The authors should explain better the contribution of work to the knowledge of his work.
- The authors should explain better how they validated the simulation program based on the proposed algorithm.
- The authors should presented more practical results.

Review 2

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Contribution of the Submission

Paper presented the development of analytical method for calculating inverse kinematics of a parallel robot

Evaluation of the Contribution

Quality of Content	(15%): 6
Significance	(15%): 6
Originality	(15%): 6
Thematic Relevance	(15%): 8
Presentation	(15%): 8
Overall Recommendation (25%):	8
Total points (out of 100) :	71

Comments for the Authors

Well written paper, author could explain the methodology of the verification in matlab in a little more detail.
Figure 3 a and b, while interesting and containing good information could be explained a little more to help the reader.

Review 3

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Contribution of the Submission

This paper has presented the development of analytical method in calculating inverse kinematics of parallel robot.

Evaluation of the Contribution

Quality of Content	(15%): 6
Significance	(15%): 6
Originality	(15%): 6
Thematic Relevance	(15%): 6
Presentation	(15%): 6
Overall Recommendation (25%):	7
Total points (out of 100) :	63

Comments for the Authors

Authors should:
explain methodology in greater depth.
Explain the rational for the work in a clearer manner
Outline the results in a clearer fashion and extract the key points and discuss these in more depth. For example why the difference between measured and designed trajectories at certain locations? How can this be overcome etc.
check for typos throughout

Regards

FAIM2019 Organising Committee

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<https://faimconference.com/>

FAIM 2019 Journal Review

1 message

FAIM 2019 Organizers <faim2019@conftool.pro>

Reply-To: faimconference2019@gmail.com

To: hendriko@pcr.ac.id

Cc: h3ndriko@gmail.com

Mon, Apr 29, 2019 at 3:50 PM

Dear Hendriko Hendriko,

CONTRIBUTION DETAILS-----
ID: 427

Title: Development of invers kinematic method for 6-dof parallel robot using analytical approach

Firstly apologies for the delay in responding regarding the Fast track Publication Option.

Papers were undergoing an follow up review to ensure suitability.

Post this review, it has been agreed that at the moment your manuscript (title and ID Included) is not adequate for fast track publication.

However an extended version with more elaborated analysis and results may be adequate for Post-Conference special issue journal.

To this end we invite you to use the FAIM Procedia of Manufacturing template and adjust your manuscript where relevant to this template and submit your final camera ready paper and attend the FAIM 219 conference.

We realise that this news will come as a disappointment however we hope that you view the experience of attending FAIM and presenting the paper at the conference as a valuable learning experience to help network and gain insights how to improve the paper with a view to publishing in a special issue journal.

Deadline for revised paper submission is May 15th, similar to the early bird registration date.

Remember to register for the conference online at faimconference.com with details of accommodation/travel etc available here.If you wish to arrange accommodation directly (rather than through the FAIM website) please use conference@ul.ie who will be able to assist you.

Best regards

FAIM 2019 Organising Committee

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FAIM 2019 - 29th International Conference on Flexible Automation and Intelligent Manufacturing

<https://www.conftool.pro/faim2019/><https://faimconference.com/>

FAIM 2019: New Submission Received. Contribution ID: 713

1 message

FAIM 2019 Organizers <faim2019@conftool.pro>

Wed, May 1, 2019 at 9:48 AM

Reply-To: info@faimconference.com

To: hendriko@pcr.ac.id

Cc: h3ndriko@gmail.com

Dear Dr. Hendriko Hendriko,

We have received your submission. Thank you.

Contribution Details

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Contribution ID : 713

Type : FINAL CAMERA READY PAPER

Title : Development of invers kinematic method for 6-dof parallel robot using analytical approach

Author(s) : Hendriko, Hendriko

Uploaded Files

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1st file : Contribution_713.pdf

Last Upload: 1st May 2019, 03:48:58am IST

2nd file : Contribution_713_2.docx

Last Upload: 1st May 2019, 03:48:58am IST

3rd file : Contribution_713_3.docx

Last Upload: 1st May 2019, 03:48:58am IST

With best regards,

Your FAIM 2019 organizers.

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